

A review of neutron list-mode data processing methods for safeguards applications

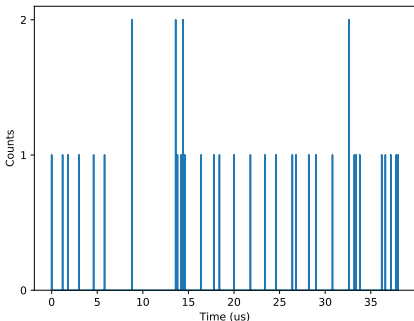
Paul Mendoza Alexis Trahan

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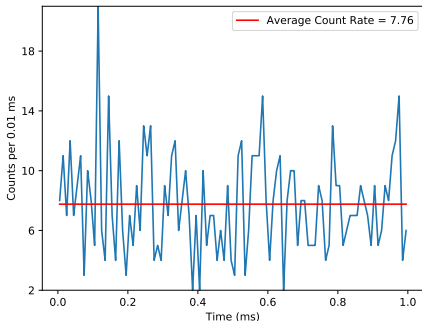


Introduction

What is list-mode data?



What is Reactor Noise?



- ❖ What do people do with this data?
- ❖ How do people collect and process this data?

Introduction

Different Processing Methods:

- ❖ Rossi-Alpha
- ❖ Feynman-Y
- ❖ Time Interval
- ❖ Pulsed Source
- ❖ Multiplicity
- ❖ et cetera

Is it possible to use multiple methods?

Are there other ways of processing this data?

Earthquake predictions[1]



Typical Assumptions

❖ Point Reactor

$$\frac{dn(t)}{dt} = \frac{\rho - \beta_{\text{eff}}}{\Lambda_{\text{eff}}} n(t) + \sum_{i=1}^I \bar{\lambda}_i \bar{C}_i$$

- n – Neutron density
- ρ – System reactivity
- β_{eff} – Delayed neutron fraction
- Λ_{eff} – Neutron generation time
- λ – Precursor decay constant
- C – Precursor concentration

❖ Single Energy Group

$$\sigma = \frac{\int \phi(E) \sigma(E) dE}{\int \phi(E) dE}$$

- σ – Single-group cross section
- ϕ – Neutron scalar flux

❖ Markov Processes

- State Transitions →
- Time Diff. Eq. →
- State probability dist.

Grouping of Processing Techniques

Nicola Pacilio[2–5]

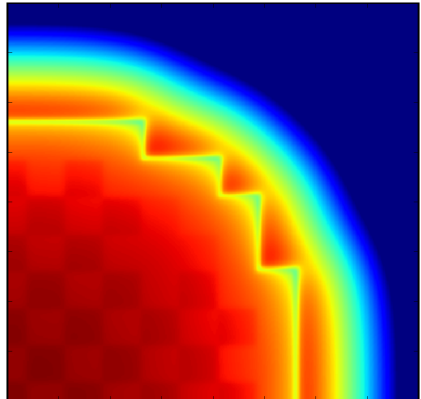
1. Probability profiles of neutron counts
2. Moments of neutron count distribution
3. Correlation among neutron counts in the time domain
4. Correlation among neutron counting level polarities in the time domain
5. Power level correlations in the frequency domain

Imre Pázsit[6–8]

1. Zero Power
2. At Power

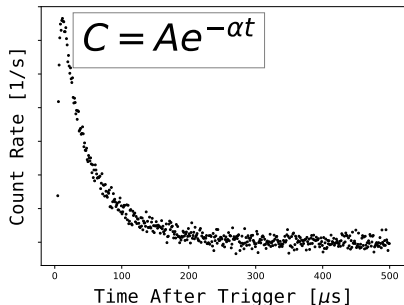
Recent Work

- ❖ Estimation of β_{eff} and Λ_{eff} for bare critical systems using the Transient Fission Matrix – TFM (2015)[9]
- ❖ Noise source reconstruction (2013)[10]
- ❖ Moderator temperature coefficient monitoring using thermocouples and neutron noise signals (2010)[11]
- ❖ Calculating β_{eff} in molten salt reactor (2014)[12], Calculating β_{eff} using different noise techniques (2012)[13]



Zero Power

- ❖ Rossi-Alpha Distributions (RAD)
 - Binned times between pulses and a triggers
 - $\alpha = \frac{\beta_{\text{eff}} - \rho}{\Lambda_{\text{eff}}}$
 - β_{eff} calculated with Nelson-Number method[14]
- ❖ Pulsed neutron source
 - Die-away distribution after a neutron generator pulse
 - The die away is similar to that of the RAD, except the use of a pulsed source more rapidly fills in the distribution



Zero Power

- ❖ Feynman-Y

$$Y(t) = A \left(1 - \frac{1 - e^{-\alpha t}}{\alpha t} \right) = \frac{\overline{c^2(t)} - \overline{c(t)}^2}{\overline{c(t)}} - 1$$

Where c is the average neutron count rate for a given gate of width t and A is a fitting parameter

- ❖ Pulse-to-Pulse time interval method

- Distribution of time between pulses
- Estimate α , along with average time between pulses

- ❖ Random Origin time interval method

- Three-parameter least squares fit to probability distribution derived by Babala[5, 15]

Traditional Safeguards Processing Schemes[16]

- ❖ Multiplicity counting can occur in passive, active, cadmium lined, or in systems with varying levels of moderation and number of detectors
- ❖ Mostly used for special nuclear material
- ❖ Singles (S), Doubles (D), Triples (T), calculated with a gate width and doubles gate utilization factor (f_d)
- ❖ Solve for fission rate (F), multiplication (M), and (α, n) fraction

$$a + bM + cM^2 + M^3 = 0$$

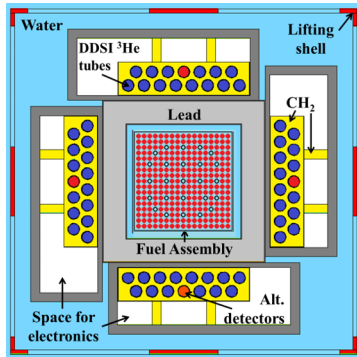
a, b, c are functions of S, D, T ,
 multiplicity moments (ν)
 and detector efficiency (ϵ)

$$F = \frac{\left[\frac{2D}{\epsilon f_d} - \frac{M(M-1)\nu_{i,2}S}{\nu_{i,1}-1} \right]}{\epsilon M^2 \nu_{s,2}}$$

$$\alpha = \frac{S}{F \epsilon \nu_{s,1} M} - 1$$

Differential Die-Away Self Interrogation Instrument

- ❖ DDSI is a nondestructive assay instrument for fuel assembly characterization
- ❖ Neutrons thermalize in water and interrogate fuel pins
- ❖ Neutron coincidence counting: detect two neutrons that are temporally correlated
 - Same fission event, same fission chain
- ❖ Record times of neutron detections
 - list-mode data



Applications

- ❖ Neutron list-mode data can be processed in all of the previously mentioned schemes
- ❖ DDSI Instrument specific caveats
 - Triples not feasible for fuel assembly measurement[17]
 - “Prompt” and “Delayed” portions of RAD from DDSI measurements are from geometry
 - Pseudo pulsed methods[5] needed with DDSI
 - Potentially redundant information
- ❖ Regression Analysis
- ❖ Train Neural network system
 - On predictor variables
 - On Raw data like [1]

Partial List of Predictor Variables

- | | | |
|--------------------------------|--------------|--|
| ❖ $S \pm \sigma_s$ (BGW) | ❖ f_d (2E) | ❖ $Y \times S/D$ (BGW) |
| ❖ $D \pm \sigma_d$ (BGW) | ❖ f_t (2G) | ❖ $\frac{\beta - \rho}{\Lambda}$ (FEY) |
| ❖ α_o^* (2G) | ❖ f_t (2E) | ❖ β_{est} |
| ❖ α_o^* (RAD) | ❖ D_f | ❖ Λ_{est} |
| ❖ α_f, α_s^* (RAD) | ❖ D_s | ❖ ρ_{est} |
| ❖ f_d (2G) | ❖ Y (BGW) | ❖ γ, α, A (RO) |

Partial Key:

- BGW – At “Best” Gate Width
- S,D – Singles Doubles
- 2G – Two gate method (assumes single exponential)
- 2E – Numeric solution for double exponential assumption
- o – Overall
- f – Gate Utilization Factor
- RO – Random Origin fitting paramters
- * – Coupled with sum percent error of the assumed exponential type

Conclusions and Acknowledgments

Conclusions

- ❖ Neutron list-mode data has been processed for reactor parameters as well as for fissile mass
- ❖ Different neutron list-mode data processing methods are expansive
- ❖ Synergistic use of calculated parameters and raw data will be attempted with current list-mode data and modern machine learning algorithms

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